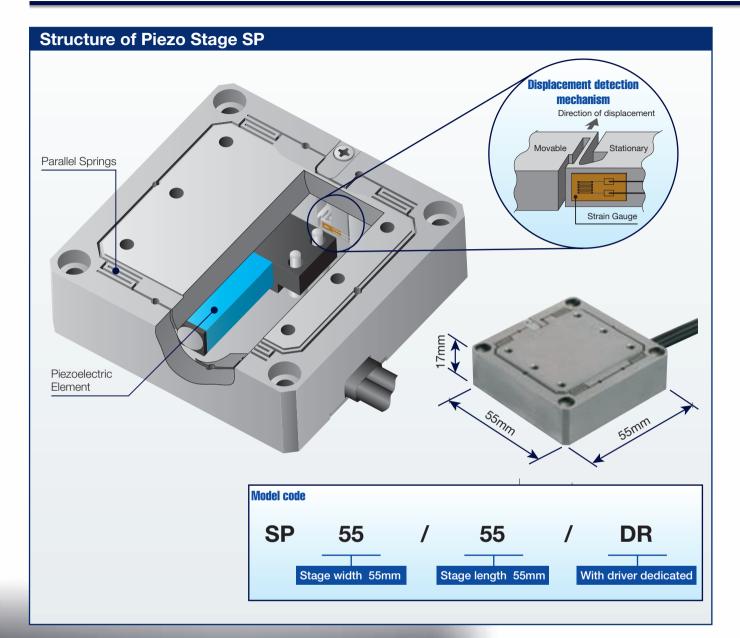
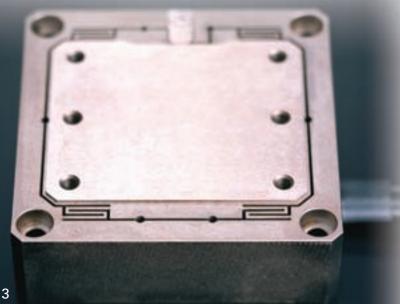






IKO Piezo Stage **SP**





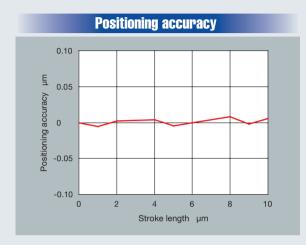
TIKE Piezo Stage SP uses the piezoelectric element as a driving source.

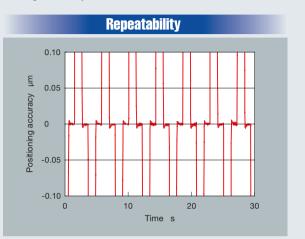
The piezoelectric element has a laminated structure which sandwiches a piezoelectric material with electrodes and expands when a voltage is applied between the electrodes (which is called "inversed piezoelectric effect"). In this case, a hysteresis generates between the applied voltage and the quantity of expansion. Piezo Stage SP performs high-accuracy super micromotion positioning by disposing a strain gauge in an optimum point obtained by a structural analysis and controlling the hysteresis by a closed control mechanism.

Features of Piezo Stage SP

High resolution and high positioning accuracy

Piezo Stage SP realizes high resolution of "10 nm" and high positioning accuracy.





Smooth micromotion

Parallel springs are provided as a mechanism to support the moving part. The springs can give a constant preload to the piezoelectric element and realize a frictionless stable micromotion feeding.

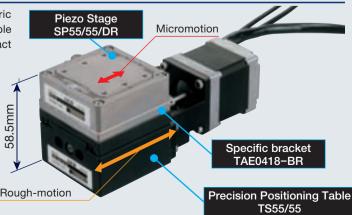
Dedicated driver having a versatile function also capable of handling pulse commands

INCO provides Piezo Stage SP together with dedicated driver that can receive pulse commands and USB commands in addition to general analog voltage commands. You can build up an optimum control system according to your system requirements.

Combination with precision positioning table

Capable of building up a rough-motion/micromotion system

A specific bracket (TAE0418-BR) enables the piezoelectric stage to be mounted on IMO Precision Positioning Table TS55/55 · CT55/55T · CT55/55. You can build up a compact rough-motion / micromotion system.



4



Specifications and Performance

Table 1 shows specifications and performance of Piezo Stage SP.

Table 1 Specifications and performance

Item	Туре	SP55/55/DR
Position sensor		Strain gauge
Stroke	μ m	10
Resolution	nm	10
Positioning accuracy	μ m	0.1
Repeatability	μ m	±0.05
Lost motion	μ m	0.05
Maximum load mass(1)	N	10
Total mass (2)	kg	0.3

Note(1) This is a maximum load that can be carried without affecting the function and performance of Piezo Stage SP.

(2) The mass of cord is not included.

Operation Specification

Piezo Stage SP works when commands are given to the dedicated driver by any of the following methods: In any of the following commanding methods, when the stage exceeds the stroke range of $10\,\mu\text{m}$, a limit signal is output to stop the stage immediately.

①Pulse command

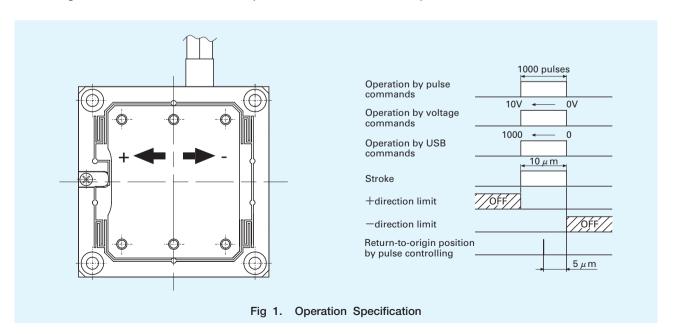
The stage moves by 10nm per pulse when "+" or "-" direction pulse command is applied. When a Return-to-Origin signal is applied, the stage moves to the center of the stroke range $(10 \,\mu\text{m})$.

②Voltage command

The stage moves at $1\mu\text{m/V}$ by an analog voltage command. In the operation by a voltage command, it is possible to offset the zero point in the stroke range ($10\mu\text{m}$) by the BIAS control on the front panel of the driver.

③USB command

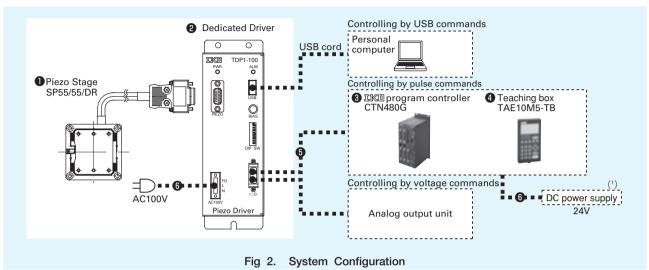
The stage moves in the unit of 10nm by a command from the USB port.



System Configuration

■Dedicated Driver

The system configuration of Piezo Stage SP is shown by Figure 2 and Table 2. The specification of the dedicated driver is shown in Table 3. The accessories of the dedicated driver are listed in Table 4.



Note(1) DC24V power supply is prepared by customer.

Remarks The cords for controlling by voltage and USB commands shall be prepared by customer.

Table 2 System configuration for controlling by pulse commands

	-	• • •	
No.	Item	Models	
0	Piezo Stage SP	SP55/55/DR	
2	Dedicated Driver	3F55/55/Dh	
3	Program controller	CTN480G	
4	Teaching box	TAE10M5-TB TAE10V1-LD Prepared by customer	
6	Pulse · Limit cord		
6	Power cable		

Remarks 1. The length of the cord between Piezo Stage SP and the dedicated driver is 3m.

2. The length of Pulse Limit cord 1.5m.

Table 3 Specifications of driver

	Item	Specification	
Control specification	Feedback	Strain gauge sensor	
	Control range	10 μm	
	Resolution	10nm	
	Pulse command	+/- direction pulse method(Photocoupler input)	
Command	Voltage command	$-10V$ to $+10V$ (1V=1 μ m)	
specification		(Bias function: 0 to+10V)	
	USB command	By communication commands from the USB port	
	Input	Return to origin in pulse controlling	
Input/Output	Output	Alarm, Positioning Completed, +Direction Limit, -Direction Limit	
specification	Analog monitor	Current position or deviation	
	Main power supply	AC100V ±10%, 50/60Hz	
Davies avents	Maximum current consumption	0.5A	
Power supply	Piezo output voltage	0 to 150V	
	Rated output current	10mA	
Ambient operating temperature and humidity		0 to 50°C, 20 to 85%RH(No condensation)	
Mass (reference)		1.6kg	

Table 4 Driver accessories

Part name	Model	Remarks
Power connector	MSTB2.5/3-STF	PHOENIX CONTACT Co., Ltd.
DIN rail fitting	DRT-1	TAKACHI ELECTRIC INDUSTRIAL Co., Ltd.

Cautions in Use

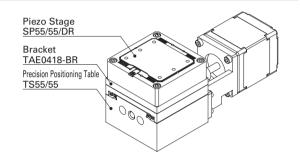
- ◆፲戊፱ Piezo Stage SP is specially adjusted together with a dedicated driver, so that the combinating of the stage and different general purpose driver is impossible.
- ◆፲戊፬ Piezo Stage SP is a precision device. Therefore, handle it with great care and do not apply any excessive load or strong impact on it.
- ◆Design the system that does not apply excessive force to cables.
- ◆Use this product in a clean environment free from water, oil, dust and other foreign matters.
- ◆Make sure that the mounting base is free from dirt and harmful protuberances.
- ◆፲戊፬ Piezo Stage SP is machined, assembled and adjusted with high accuracy. Accordingly, never disassemble or remodel it in any case.

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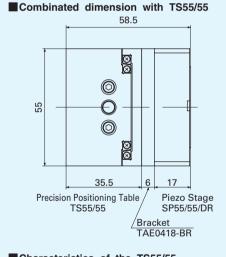
Combination of **IKO** Precision Positioning Table

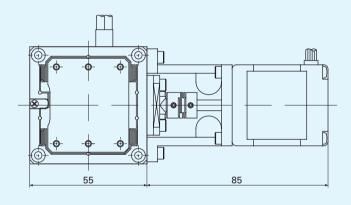
IKO Piezo Stage SP can be mounted on IKO Precision Positioning Table TS55/55 · CT55/55T · CT55/55 by using the dedicated attachment. This allows to build a compact rough-fine positioning mechanism.

For details of specifications and performance of IKO Precision Positioning Table TS55/55 · CT55/55T · CT55/55, refer to the catalog of Precision Positioning Table Compact Series "CAT-57122" or "CAT-57134".

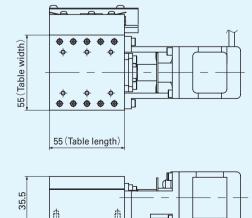


Combination with TS55/55





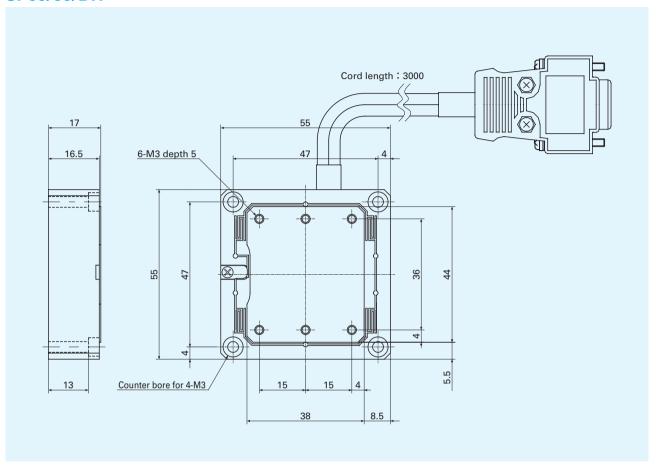


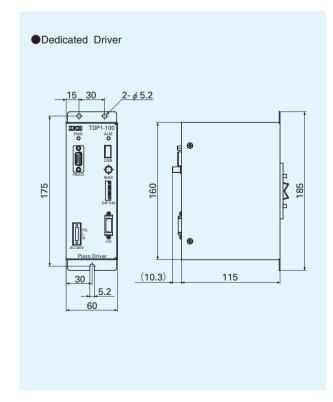


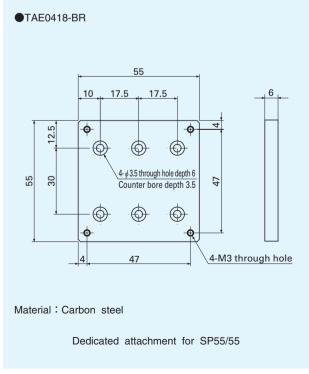
Accuracy

ltem		Performance
Stroke length	mm	土7.5
Positioning accuracy	mm	0.005
Repeatability	mm	±0.002
Parallelism in operation A	mm	0.005
Parallelism in operation B	mm	0.015
Allowable load	N	20
Table inertia J_{T}	\times 10 ⁻⁵ kg • m ²	0.01
Starting torque T_0	N∙m	0.03

SP55/55/DR







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