

The IKO logo is displayed in a bold, red, sans-serif font.

Super Precision Positioning Table

TX CTX



CAT-57145

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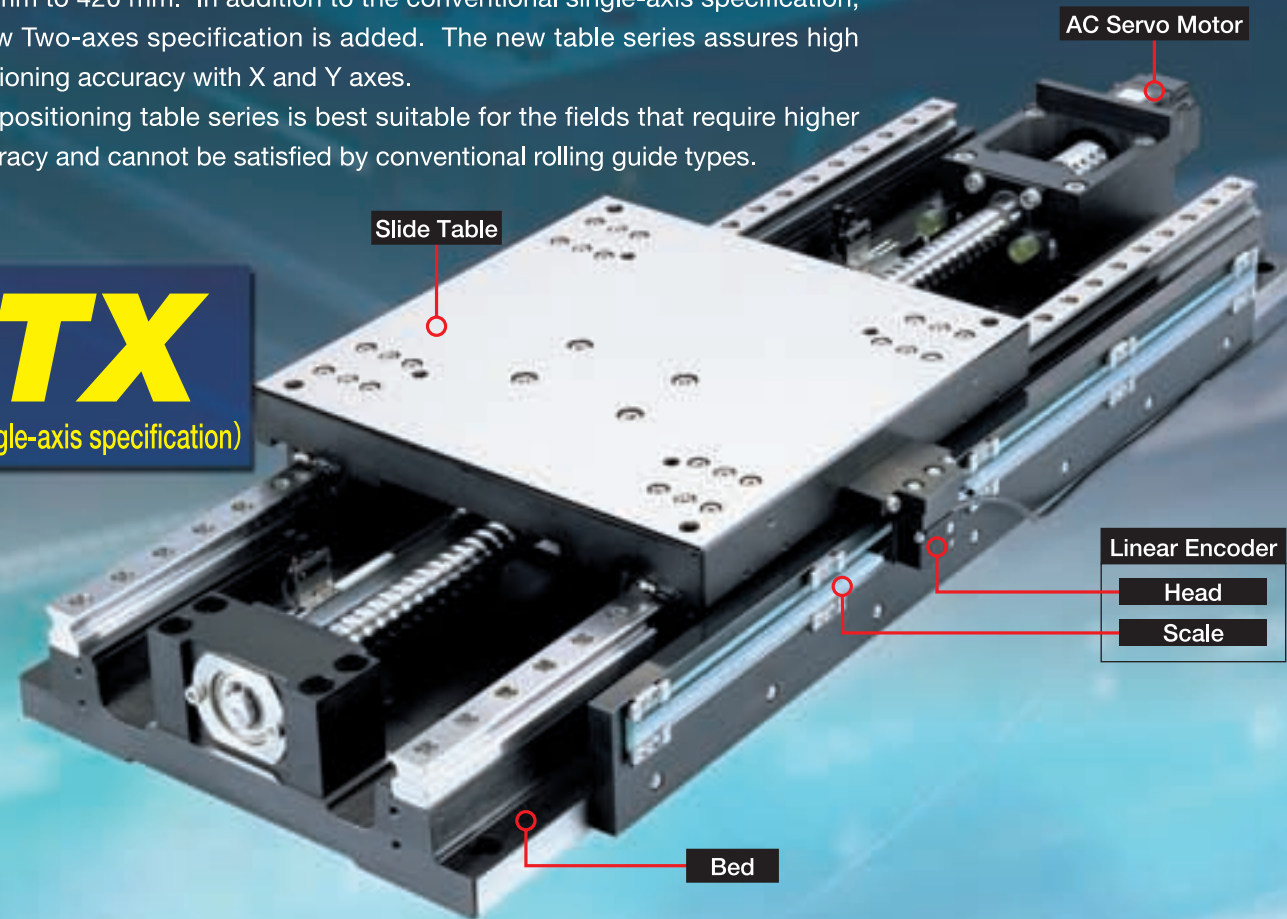
TX Series of Rolling Guide Type Realizing Ultimate Positioning Performance

IJKO High Precision Positioning Table TX has realized almost as high positioning performance as the air stage by incorporated the ultimate rolling guide IJKO Linear Roller Way Super X in IJKO Precision Positioning Table LH which is well-known for high accuracy and high rigidity as the base.

IJKO High Precision Positioning Table TX has four kinds of table widths from 120 mm to 420 mm. In addition to the conventional single-axis specification, a new Two-axes specification is added. The new table series assures high positioning accuracy with X and Y axes.

This positioning table series is best suitable for the fields that require higher accuracy and cannot be satisfied by conventional rolling guide types.

TX
(Single-axis specification)



IJKO High Precision Positioning Table TX and CTX

Use in low and medium vacuum condition

No influence to a vacuum environment by an air flow in an air stage. Can be supplied with vacuum environment grease on request. Please consult IJKO.

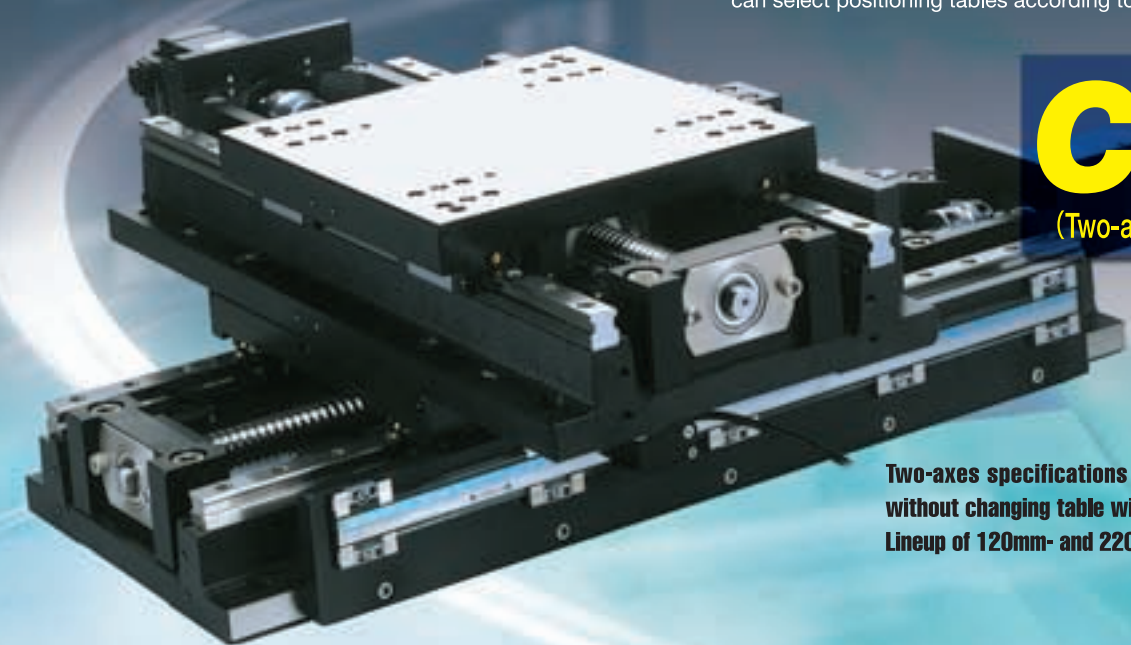
For clean room application

Low dust generating clean grease is available as an option. Please consult IJKO.

Wide variation

This series provides four table sizes ranging from 120 mm to 420 mm. Tables of double-axis specifications are manufactured in series to assure accuracies in X- and Y-axis combination. You can select positioning tables according to your applications.

CTX
(Two-axes specification)

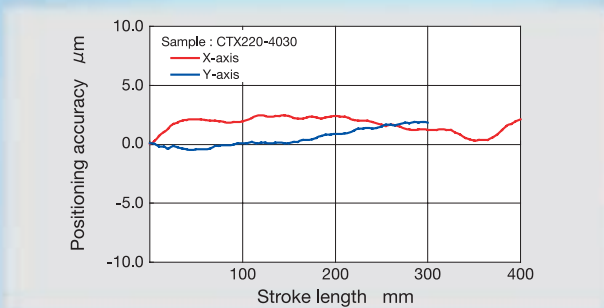


Two-axes specifications using X- and Y- tables without changing table widths are now on stage. Lineup of 120mm- and 220mm-wide tables

Ultimate positioning performance

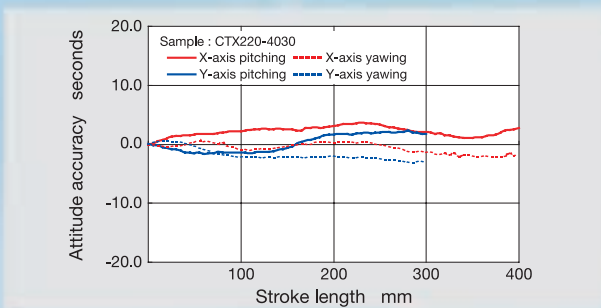
High positioning accuracy and resolution due to super-high accuracy linear encoder

By directly feeding back positional information from the super-high accuracy linear encoder of a resolution of 0.016 μm , a full-closed-loop control system is established. This control system assures high positioning accuracy in the whole stroke length.



Ultimate running accuracy by adopting Linear Roller Way Super X

Rolling guide type of ultimate running accuracy thanks to good combination of components that are machined and assembled very accurately and IJKO Linear Roller Way Super X that demonstrates the best running accuracy.



Always demonstrating stable performance by the employment of Linear Roller Way Super X

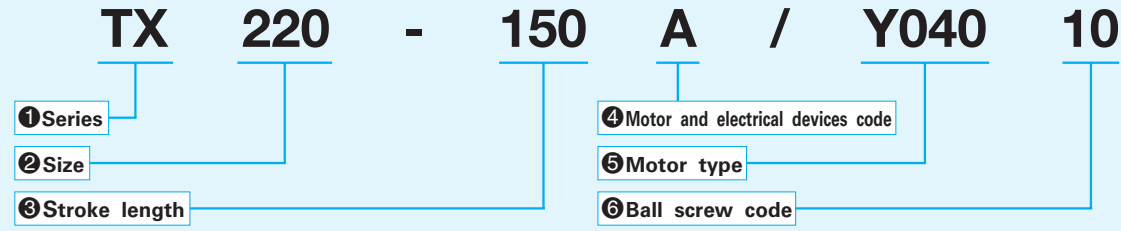
By using IJKO Linear Roller Way Super X which demonstrates excellent rigidity under high load capacity, this series of tables can demonstrate high rigidity and specifically stable performance in an environment of fluctuating loads.

Linear Roller Way Super X



Identification Number and Specification

Example of identification number (Single axis)



| | |
|--------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1 Series | TX : Super Precision Positioning Table TX (Single axis) |
| 2 Size | Width of table Select from Table 1. |
| 3 Stroke length | Select from Table 1. |
| 4 Motor and electrical devices code | A : with motor and electrical devices Super Precision Positioning Table TX is operated by full closed control. Electrical devices, AC servo motor, driver, serial exchange unit, motor code, encoder cord and serial exchange cord are appended to the table. |
| 5 Motor type | Select servomotor from Table 2. |
| 6 Ball screw code | 5 : 5mm lead 10 : 10mm lead |

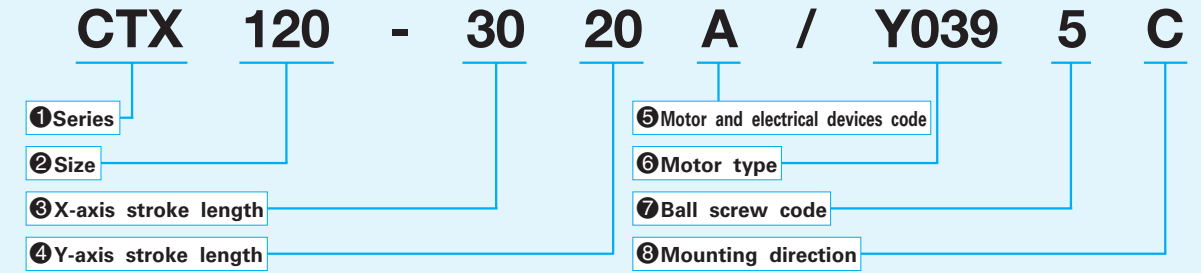
Table 1 Models and stroke lengths

| Model | Width of table mm | Stroke length mm | | | | |
|--------------|-------------------|------------------|-----|-----|-----|-----|
| | | 100 | 150 | 200 | 250 | 300 |
| TX120 | 120 | 100 | 150 | 200 | 250 | 300 |
| TX220 | 220 | 150 | 200 | 250 | 300 | 400 |
| TX320 | 320 | 300 | 400 | 500 | — | — |
| TX420 | 420 | 500 | 600 | 800 | — | — |

Table 2 Motor types

| Model | Motor code | |
|--------------|------------|---------------|
| | With brake | Without brake |
| TX120 | Y039 | Y043 |
| TX220 | Y040 | Y044 |
| TX320 | Y041 | Y045 |
| TX420 | Y042 | Y046 |

Example of identification number (X-Y specification)



| | |
|----------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1 Series | CTX : Super Precision Positioning Table (X-Y specification) |
| 2 Size | Width of table Select from Table 3. Combination of tables in different sizes is possible. |
| 3 X-axis stroke length 4 Y-axis stroke length | Select from Table 3. Indicate the stroke length by "cm". |
| 5 Motor and electrical devices code | A : with motor and electrical devices Super Precision Positioning Table TX is operated by full closed control. Electrical devices, AC servo motor, driver, serial exchange unit, motor code, encoder cord and serial exchange cord are appended to the table. |
| 6 Motor type | Select servomotor from Table 4. |
| 7 Ball screw code | 5 : 5mm lead 10 : 10mm lead |
| 8 Mounting direction | No symbol : X-axis motor locates 90 degrees from Y-motor in clockwise direction when looking down. C : X-axis motor locates 90 degrees from Y-motor in counterclockwise direction when looking down. |

Table 3 Models and stroke lengths

| Model | Width of table mm | Stroke length mm | |
|---------------|-------------------|------------------|--------|
| | | X-axis | Y-axis |
| CTX120 | 120 | 100 | 100 |
| | | 200 | 100 |
| | | 200 | 200 |
| | | 300 | 200 |
| CTX220 | 220 | 200 | 200 |
| | | 300 | 200 |
| | | 300 | 300 |
| | | 400 | 300 |

Table 4 Motor types

| Model | Motor code | |
|---------------|------------|---------------|
| | With brake | Without brake |
| CTX120 | Y039 | Y043 |
| CTX220 | Y040 | Y044 |

Remark : For the table with brake, motor with brake is mounted on Y-axis only. For example, if Y043 is selected, X-axis has Y039 and Y-axis has Y043.

Accuracy

Table 5 Accuracy

| Model | Stroke length | | Positioning accuracy | Repeatability | Lost motion | Parallelism in table operation A | Attitude accuracy (°) sec. | Straightness in vertical Straightness in horizontal | Squareness of X-Y travel | | |
|-------------|---------------|--------|----------------------|---------------|-------------|----------------------------------|----------------------------|--------------------------------------------------------|--------------------------|-------|-------|
| | X-axis | Y-axis | | | | | | | | | |
| Single axis | TX120 | 100 | 0.003 | ±0.0005 | 0.001 | 0.005 | 5 | 0.003 | — | | |
| | | 150 | | | | | | | | | |
| | | 200 | 0.004 | | | | | | | | |
| | | 250 | | | | | | | | | |
| | | 300 | | | | | | | | | |
| | TX220 | 150 | 0.003 | ±0.0005 | 0.001 | 0.005 | 5 | 0.003 | — | | |
| | | 200 | 0.004 | | | | | | | | |
| | | 250 | | | | | | | | | |
| | | 300 | 0.005 | | | | | | | | |
| | TX320 | 300 | 0.004 | ±0.0005 | 0.001 | 0.006 | 6 | 0.004 | — | | |
| | | 400 | 0.005 | | | | | | | | |
| | | 500 | | | | | | | | | |
| TX420 | 500 | 0.005 | ±0.0005 | 0.001 | 0.007 | 7 | 0.005 | — | | | |
| | 600 | 0.006 | | | | | | | | | |
| | 800 | 0.008 | | | | | | | | | |
| X-Y axis | CTX120 | 100 | 100 | 0.005 | ±0.0005 | 0.001 | 0.008 | 8 | 0.005 | 0.005 | |
| | | 200 | 100 | | | | | | | 0.010 | |
| | | 200 | 200 | | | | | | | | |
| | | 300 | 200 | | | | | | | | |
| | CTX220 | 200 | 200 | 0.006 | ±0.0005 | 0.001 | 0.009 | 9 | 0.006 | 0.005 | |
| | | 300 | 200 | | | | | | | | 0.010 |
| | | 300 | 300 | | | | | | | | |
| | | 400 | 300 | | | | | | | | |

Note(1) Amounts in the table show pitching and yawing.

Maximum Speed

Maximum speed of Super Precision Positioning Table TX is shown in Table 6.

Maximum speed and resolution are given by the lead of ball screw and driver's parameter (Electric gear).

Actual speed should not exceed values in Table 6.

Table 6 Maximum speeds

| Lead of ball screw mm | Electron gear | | Maximum speed mm/sec |
|-----------------------|---------------|-------------|----------------------|
| | Numerator | Denominator | |
| 5 | 1 | 1 | 15.6 |
| | 2 | 1 | 31.2 |
| | 4 | 1 | 62.5 |
| | 8 | 1 | 125 |
| | 16 | 1 | 250(224) |
| 10 | 1 | 1 | 15.6 |
| | 2 | 1 | 31.2 |
| | 4 | 1 | 62.5 |
| | 8 | 1 | 125 |
| | 16 | 1 | 250 |
| | 32 | 1 | 500(448) |

Remark 1. : Values in () are applicable for TX320 and TX420.

2. : Actual maximum speed may be affected by load condition.

3. : Resolution is obtained by the following formula. The pitch of scale is 4 micron meter.

$$\text{Resolution} = \frac{\text{Pitch of scale}}{256} \times \frac{\text{Electric gear numerator}}{\text{Electric gear denominator}} [\mu\text{m}]$$

Sensor Specification

Table 7 Specifications of sensor

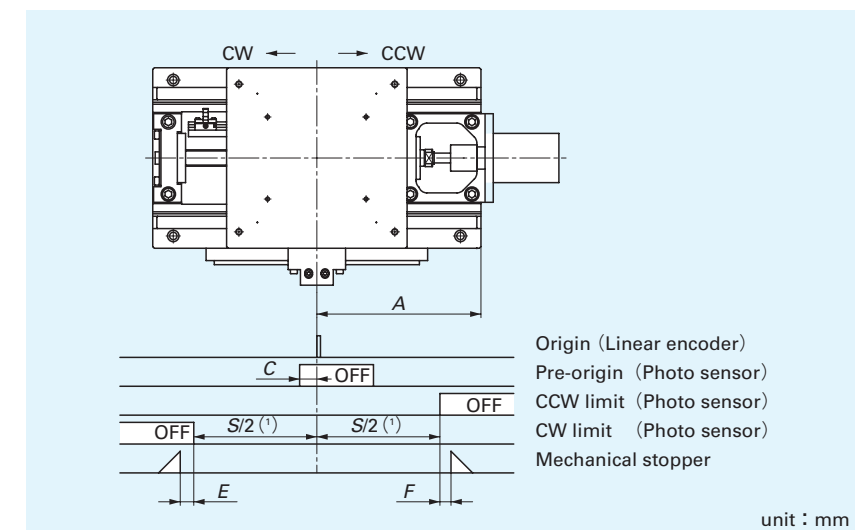
| Sensor Item | Pre-origin, CW limit, CCW limit |
|----------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Type | Photo sensor |
| Power supply voltage | DC5~24V ±10% |
| Current consumption | 30mA or less |
| Output | Open collector • Max. current : 50mA • Applied voltage : DC30V or less • Residual voltage : 0.7V or less at 50mA in-flow current 0.4V or less at 16mA in-flow current |
| Output operation | When approaching : ON |
| Operation indicator | Operation indicator LED (red) |
| Circuit diagram | |

Table 8 Specifications of connector

| Pin No. | Signal name | Sensor-side connector type | Opposite-side connector type |
|---------|-------------|----------------------------|------------------------------|
| 1 | — | Cap housing 172160-1 | Plug housing 172168-1 |
| 2 | Pre-origin | | |
| 3 | CW limit | | |
| 4 | CCW limit | Contactor 170365-1 | Contactor 170363-1 |
| 5 | Power input | | |
| 6 | GND | | |

Remarks1. : The origin signal of linear encoder from driver can be used as origin point.
2. : Connector is made by Tyco Electronics Co., Ltd.
3. : Opposite-side connector and contactor are not appended.

Table 9 Sensor timing chart



| Model number | Ball screw lead | A | C | E | F |
|--------------|-----------------|---------|---|-----|-----|
| TX120 | 5 | L/2 (1) | 3 | 5.5 | 4.5 |
| CTX120 | 10 | | 7 | | |
| TX220 | 5 | L/2 (1) | 3 | 14 | 10 |
| CTX220 | 10 | | 7 | | |
| TX320 | 5 | L/2 (1) | 3 | 20 | 15 |
| | 10 | | 7 | | |
| TX420 | 5 | L/2 (1) | 3 | 18 | 15 |
| | 10 | | 7 | | |

Note(1) Refer to dimension tables on page 11 to 14.

Remark : For X-Y axis table, specification of each axis are the same as those of single axis.

Table Inertia and Starting Torque

Table 10 Table inertia, coupling inertia and starting torque

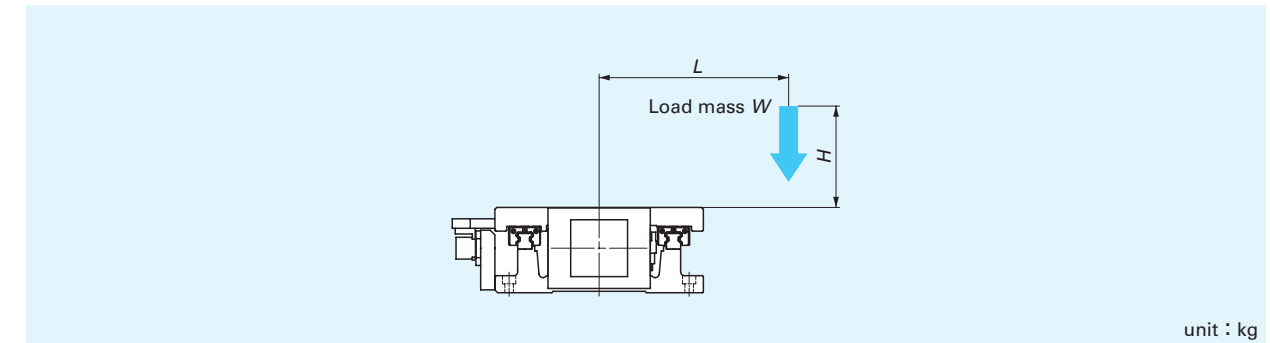
| Mode number | Stroke length mm | | Table inertia J_T $\times 10^{-5} \text{kg} \cdot \text{m}^2$ | | Coupling inertia J_c $\times 10^{-5} \text{kg} \cdot \text{m}^2$ | Starting torque T_0 N · m | |
|-------------|------------------|--------|--------------------------------------------------------------------|-----------|-----------------------------------------------------------------------|--------------------------------|------|
| | X-axis | Y-axis | Lead 5mm | Lead 10mm | | | |
| Single axis | TX120 | 100 | | 1.3 | 1.8 | 0.29 | 0.07 |
| | | 150 | | 1.5 | 2.0 | | |
| | | 200 | | 1.6 | 2.2 | | |
| | | 250 | | 1.8 | 2.4 | | |
| | | 300 | | 2.0 | 2.6 | | |
| | TX220 | 150 | | 5.2 | 7.0 | 0.85 | 0.12 |
| | | 200 | | 5.8 | 7.6 | | |
| | | 250 | | 6.4 | 8.2 | | |
| | | 300 | | 7.1 | 8.8 | | |
| | TX320 | 300 | | 20 | 26 | 0.85 | 0.26 |
| 400 | | | 23 | 29 | | | |
| 500 | | | 26 | 32 | | | |
| TX420 | 500 | | 30 | 39 | 0.85 | 0.30 | |
| | 600 | | 33 | 42 | | | |
| | 800 | | 39 | 48 | | | |
| X-Y axis | CTX120 | 100 | 100 | 2.1 | 4.7 | 0.29 | 0.07 |
| | | 200 | 100 | 2.4 | 5.1 | | |
| | | 200 | 200 | 2.5 | 5.8 | | |
| | | 300 | 200 | 2.9 | 6.2 | | |
| | | 200 | 200 | 8.2 | 16.9 | | |
| | 300 | 200 | 9.5 | 18.1 | | | |
| | 300 | 300 | 9.8 | 19.3 | | | |
| | 400 | 300 | 11.0 | 20.5 | | | |

Remark : For X-Y axis table, values in the table show of X axis. Values of Y axis are applicable to the single axis in the table.

Maximum Load Mass

Maximum load masses of Super Precision Positioning Table TX are shown in Table 11. The values in the table are reference values for the maximum mass that can be mounted on each models used in horizontal position and vary much depending on the position of load mass.

Table 11 Maximum Load Mass



| Model | Ball screw lead mm | Height H mm | Length L mm | | | | | | | | |
|-------|--------------------|---------------|---------------|-----|-----|-----|-----|-----|-----|-----|------|
| | | | 0 | 100 | 200 | 300 | 400 | 500 | 600 | 800 | 1000 |
| TX120 | 5 | 0 | 310 | 94 | 55 | 39 | 30 | 25 | 21 | 16 | 13 |
| | | 200 | 260 | 92 | 55 | 39 | 30 | 25 | 21 | 16 | 13 |
| | | 400 | 200 | 87 | 53 | 38 | 30 | 25 | 21 | 16 | 13 |
| | | 600 | 160 | 80 | 52 | 38 | 30 | 24 | 21 | 16 | 13 |
| | 10 | 0 | 180 | 74 | 43 | 30 | 24 | 19 | 16 | 12 | 10 |
| | | 200 | 150 | 67 | 42 | 30 | 23 | 19 | 16 | 12 | 10 |
| | | 400 | 100 | 58 | 39 | 29 | 23 | 19 | 16 | 12 | 9.9 |
| | | 600 | 75 | 50 | 35 | 27 | 22 | 18 | 16 | 12 | 9.8 |
| TX220 | 5 | 0 | 410 | 260 | 170 | 120 | 97 | 80 | 68 | 53 | 43 |
| | | 200 | 410 | 260 | 170 | 120 | 97 | 80 | 68 | 53 | 43 |
| | | 400 | 410 | 250 | 160 | 120 | 96 | 80 | 68 | 53 | 43 |
| | | 600 | 410 | 230 | 160 | 120 | 95 | 79 | 68 | 53 | 43 |
| | 10 | 0 | 270 | 210 | 130 | 96 | 76 | 63 | 53 | 41 | 33 |
| | | 200 | 270 | 190 | 130 | 95 | 75 | 62 | 53 | 41 | 33 |
| | | 400 | 270 | 170 | 120 | 91 | 73 | 61 | 52 | 41 | 33 |
| | | 600 | 230 | 150 | 110 | 87 | 71 | 60 | 51 | 40 | 33 |
| TX320 | 5 | 0 | 820 | 820 | 620 | 470 | 380 | 320 | 270 | 210 | 180 |
| | | 200 | 820 | 820 | 620 | 470 | 380 | 320 | 270 | 210 | 180 |
| | | 400 | 820 | 820 | 610 | 470 | 380 | 320 | 270 | 210 | 180 |
| | | 600 | 820 | 820 | 600 | 460 | 370 | 320 | 270 | 210 | 180 |
| | 10 | 0 | 380 | 380 | 380 | 370 | 300 | 250 | 210 | 170 | 140 |
| | | 200 | 380 | 380 | 380 | 360 | 290 | 250 | 210 | 170 | 140 |
| | | 400 | 380 | 380 | 380 | 350 | 290 | 240 | 210 | 160 | 140 |
| | | 600 | 380 | 380 | 380 | 340 | 280 | 240 | 210 | 160 | 130 |
| TX420 | 5 | 0 | 800 | 800 | 800 | 660 | 540 | 450 | 390 | 310 | 250 |
| | | 200 | 800 | 800 | 800 | 650 | 530 | 450 | 390 | 310 | 250 |
| | | 400 | 800 | 800 | 800 | 650 | 530 | 450 | 390 | 310 | 250 |
| | | 600 | 800 | 800 | 800 | 640 | 530 | 450 | 390 | 310 | 250 |
| | 10 | 0 | 360 | 360 | 360 | 360 | 360 | 350 | 310 | 240 | 200 |
| | | 200 | 360 | 360 | 360 | 360 | 360 | 350 | 300 | 240 | 200 |
| | | 400 | 360 | 360 | 360 | 360 | 360 | 350 | 300 | 240 | 200 |
| | | 600 | 360 | 360 | 360 | 360 | 360 | 340 | 300 | 240 | 200 |

Remarks 1. : The above values are obtained by calculating the mass for which the rating life of the ball screw or linear motion rolling guide becomes 18,000 hours when the table is operated continuously at the maximum speed (for each size), and 0.2s each, at acceleration and at deceleration.

2. : For CTX, consider load mass for each axis independently.

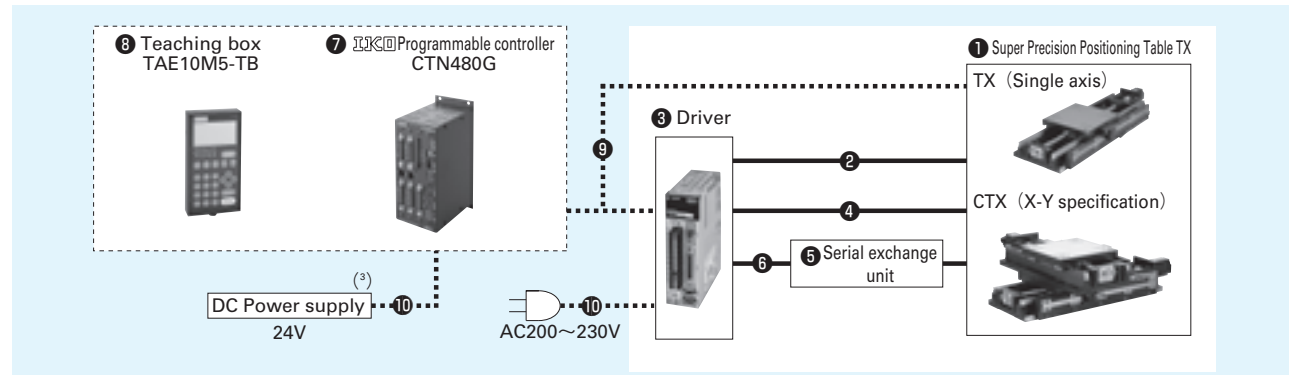
1N=0.102kgf=0.2248lbs.
1mm=0.03937inch

Electric Devices

System configuration

Super Precision Positioning Table TX is operated by highly accurate full-closed-loop control and electric devices (AC servo motor, driver, serial exchange unit, motor code, encoder code and serial exchange unit cord) to each model are designated to achieve best performance. Models of these devices are shown below.

Exclusive controller, pulse and limit codes are prepared by customer.



| Items | Model code | | | | | | |
|--------------------------------------------|-----------------------------|-----------------|---------------|-------|-------------------------|--------------------------|------|
| ① Super Precision Positioning Table TX | TX120 | TX220 | TX320 | TX420 | CTX120 | CTX220 | |
| Motor without brake | Motor code ⁽¹⁾ | Y039 | Y040 | Y041 | Y042 | Y039 | Y040 |
| | ② Motor cord ⁽¹⁾ | JZSP-CSM02-03-E | | | JZSP-CSM03-03-E | JZSP-CSM02-03-E 2pcs. | |
| Motor with brake ⁽²⁾ | Motor code ⁽¹⁾ | Y043 | Y044 | Y045 | Y046 | Y043 | Y044 |
| | ② Motor cord ⁽¹⁾ | JZSP-CSM12-03-E | | | JZSP-CSM13-03-E | JZSP-CSM12-03-E 2pcs. | |
| ③ Driver ⁽¹⁾ | SGDS-02A02A-E | SGDS-04A02A-E | SGDS-08A02A-E | | SGDS-02A02A-E 2units | SGDS-04A02A-E 2units | |
| ④ Encoder cord ⁽¹⁾ | JZSP-CSP01-03-E | | | | | | |
| ⑤ Serial exchange unit ⁽¹⁾ | JZDP-D003-000-E | | | | | | |
| ⑥ Serial exchange unit cord ⁽¹⁾ | JZSP-CLP70-03-E | | | | | | |
| ⑦ Programmable controller | CTN480G | | | | | | |
| ⑧ Teaching box | TAE10M5-TB | | | | | | |
| ⑨ Pulse and limit cord | TAE10M7-LD□□ (TAE10M8-LD□□) | | | | | | |
| ⑩ Power supply cord ⁽³⁾ | Prepared by customer | | | | | | |

Note⁽¹⁾ Delivered with AC servo motor (Yaskawa Electric Corporation), motor code, driver, encoder cord, serial exchange unit and serial exchange unit cord.

⁽²⁾ For "with brake model", power supply for brake release is needed.

⁽³⁾ DC24V power supply is prepared by customer.

Remarks 1.: For "with brake model" in X-Y axis table, brake is applicable to Y axis only.

2.: The length of motor cord and encoder cord are 3 m each.

3.: Cord in () have high bending resistance.

4.: The length of pulse and limit cord can be specified by □□ in the end of supplemental code. Selecting length is up to 20 m in increments of 1 m.

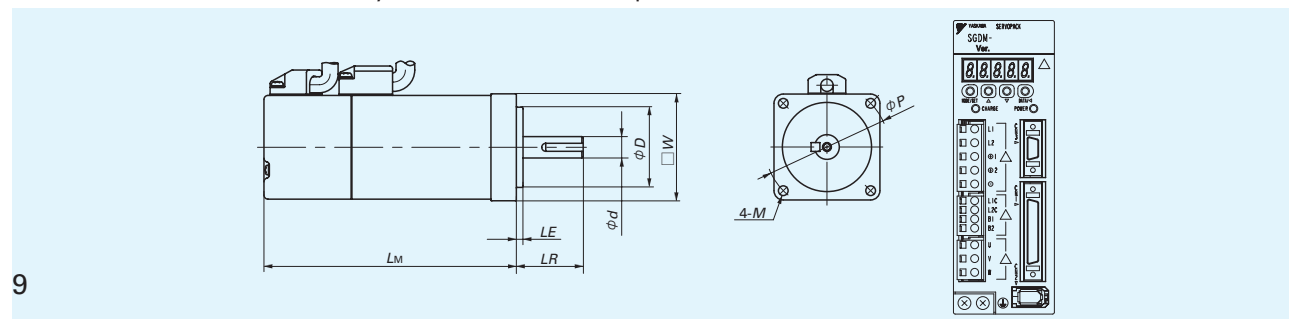
※The length under 10 m is also selected by two digits. (Example of 3 m: TAE10M7-LD03)

5.: The length of pulse and limit cord is 1.5 m.

6.: For X-Y axis table, two pieces each of pulse and limit cord are necessary.

Specifications of motor and driver

AC servo motor and driver by Yaskawa Electric Corporation (RoHS conformed)



Motor specifications

| Motor code | Motor code | Power supply voltage V | Rated output W | Rated torque N·m | Instantaneous maximum torque N·m | Rated number of revolution r/min | Motor inertia $J_m \times 10^{-4} \text{ kg} \cdot \text{m}^2$ | Encoder specification | Mass kg |
|------------|-----------------|------------------------|----------------|------------------|----------------------------------|----------------------------------|----------------------------------------------------------------|--------------------------------------|---------|
| Y039 | SGMAS-02ACA21-E | 200 | 200 | 0.637 | 1.91 | 3000 | 0.116 | Incremental 17bits (131072pulse/rev) | 0.9 |
| Y040 | SGMAS-04ACA21-E | | 400 | 1.27 | 3.82 | | 0.190 | | 1.2 |
| Y041 | SGMAS-06ACA21-E | | 600 | 1.91 | 5.73 | | 0.326 | | 1.7 |
| Y042 | SGMAS-08ACA21-E | | 750 | 2.39 | 7.16 | | 0.769 | | 2.5 |
| Y043 | SGMAS-02ACA2C-E | | 200 | 0.637 | 1.91 | | 0.180 | | 1.5 |
| Y044 | SGMAS-04ACA2C-E | | 400 | 1.27 | 3.82 | | 0.254 | | 1.8 |
| Y045 | SGMAS-06ACA2C-E | | 600 | 1.91 | 5.73 | | 0.390 | | 2.4 |
| Y046 | SGMAS-08ACA2C-E | | 750 | 2.39 | 7.16 | | 0.940 | | 3.2 |

Motor mounting dimension

| Motor code | □WXLM | LR | LE | d | D | P | M |
|------------|----------|----|----|----|----|----|------|
| Y039 | 60×80 | 30 | 3 | 14 | 50 | 70 | φ5.5 |
| Y040 | 60×98.5 | 30 | 3 | 14 | 50 | 70 | φ5.5 |
| Y041 | 60×124.5 | 30 | 3 | 14 | 50 | 70 | φ5.5 |
| Y042 | 80×115 | 40 | 3 | 16 | 70 | 90 | φ7 |
| Y043 | 60×120 | 30 | 3 | 14 | 50 | 70 | φ5.5 |
| Y044 | 60×138.5 | 30 | 3 | 14 | 50 | 70 | φ5.5 |
| Y045 | 60×172 | 30 | 3 | 14 | 50 | 70 | φ5.5 |
| Y046 | 80×160 | 40 | 3 | 16 | 70 | 90 | φ7 |

Driver specifications

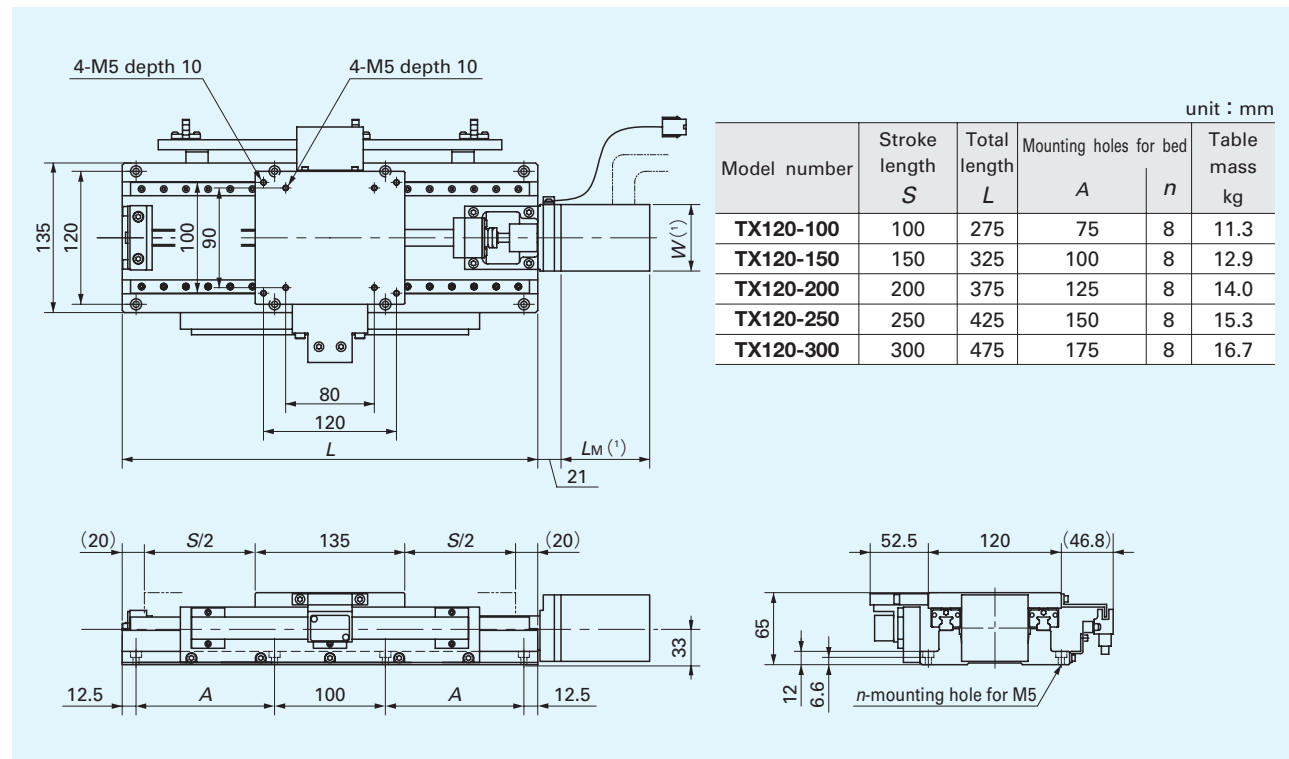
| Item | Model code of driver | | | |
|----------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------|-------------|-------------|-------------|
| | SGDS-02A02A | SGDS-04A02A | SGDS-08A02A | |
| Applicable motor code | Y039 · Y043 | Y040 · Y044 | Y041 · Y045 | Y042 · Y046 |
| Rated output | 200W | 400W | 600W | 750W |
| Command input pulse | Selection one from Symbol with pulse line, CCW or CW with pulse line, two phases pulse with 90-degree difference (A-phases or B-phases). | | | |
| Type of command input pulse | Line driver | | | |
| Capability of command input speed | 1Mpps in maximum | | | |
| Main power supply voltage | Single phase AC200~230V -15~+10% 50/60Hz | | | |
| Control circuit supply voltage | Single phase AC200~230V -15~+10% 50/60Hz | | | |
| Continuous rated current Arms | 2.1 | 2.8 | 5.5 | |
| Maximum consumption current Arms | 6.5 | 8.5 | 16.9 | |
| Ambient temperature in operation | 0~+55°C | | | |
| Ambient temperature in storage | -20~+85°C | | | |
| Ambient temperature in operation and storage | 90%RH or less (Keep dewdrop free) | | | |
| Mass (Ref.) kg | 0.7 | 0.9 | 1.4 | |

Caution in Use

- Super Precision Positioning Table TX is a precision equipment. A careful handling is strongly required. Do not apply any excessive force or heavy shock.
- Make sure the mounting base to be free from dirt and harmful foreign objects.
- Good flatness is required for mounting bed to assure positioning accuracy. 8μm or better is recommended.
- Grease is applied to the linear motion rolling guide and ball screw at delivery. Dust preventive cover is required to protect the inside of table from foreign particles or dusts. In case foreign particles or dusts enter into the table, intensive cleaning and re-greasing are necessary.
- The re-lubrication interval varies depending on the operating conditions of the table. A six month interval is generally recommended. If the table operation consists of reciprocating motions with many cycles and long strokes, re-lubrication in every three months with replacing old grease is recommended.
- Super Precision Positioning Table TX is machined, assembled and adjusted very precisely. Therefore, never disassemble or modify the table.
- Linear encoder is made of glass. Great care is necessary not to apply load and/or shock to it.
- Please make sure that surface of linear scale must be kept clean by ethyl alcohol or alternative cleaning solution, otherwise, malfunction or irregular operation may happen. In the application of dusty environment, dust protective cover for linear encoder is recommended.

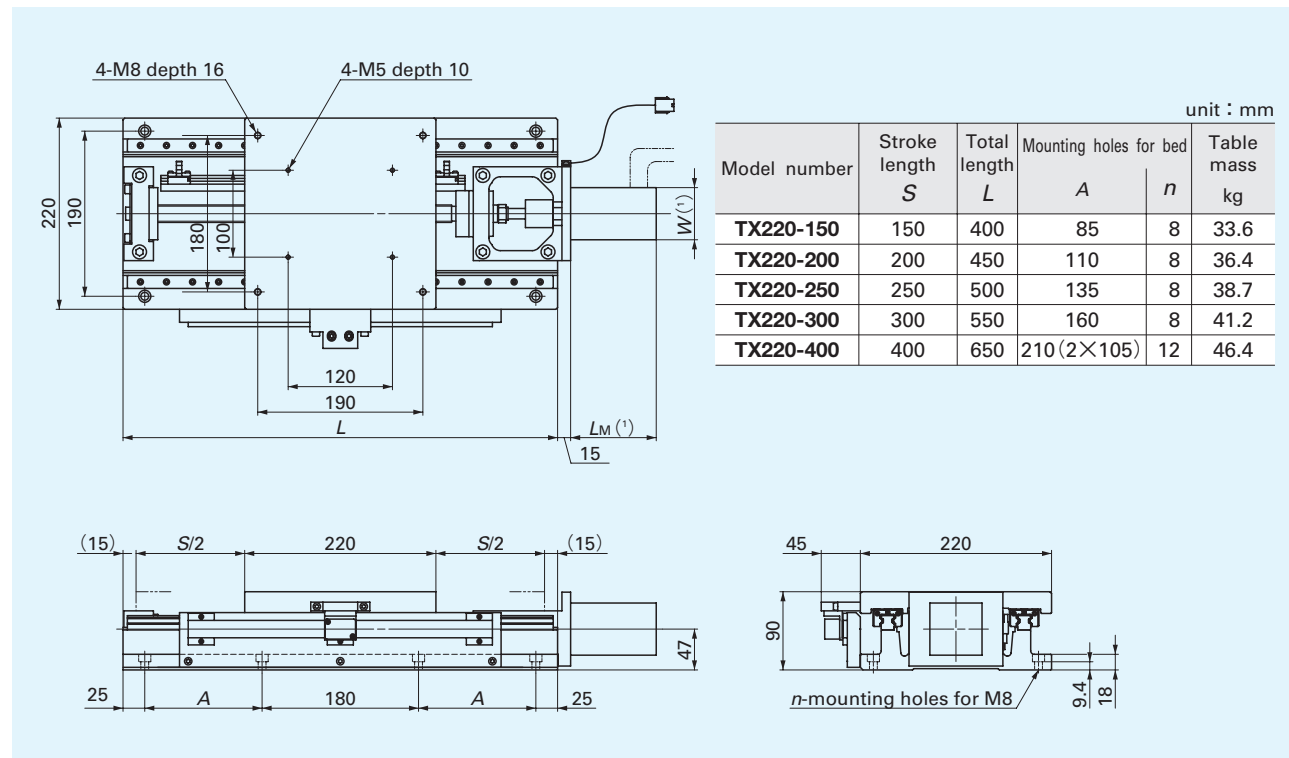
1N=0.102kgf=0.2248lbs.
1mm=0.03937inch

TX120



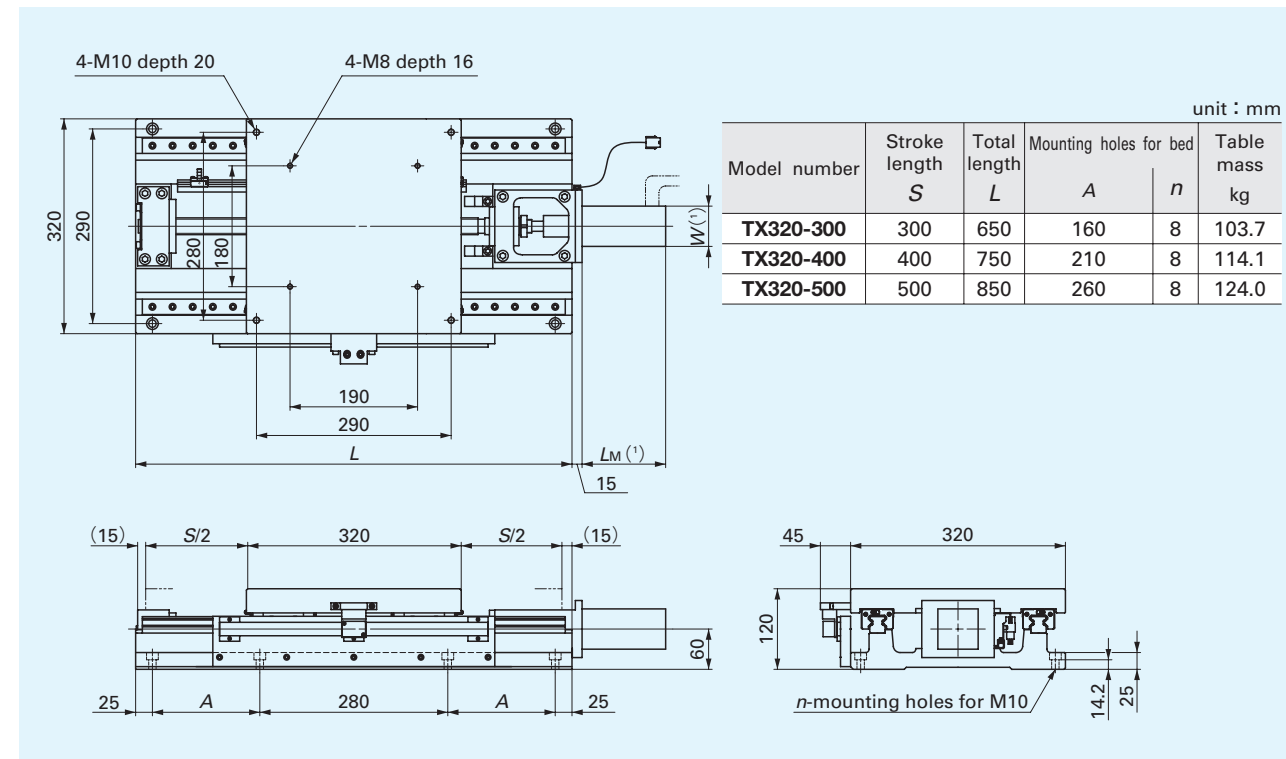
Note⁽¹⁾ : For dimensions of motors, refer page 9-10.
 (2) : Motor weight is not included.

TX220



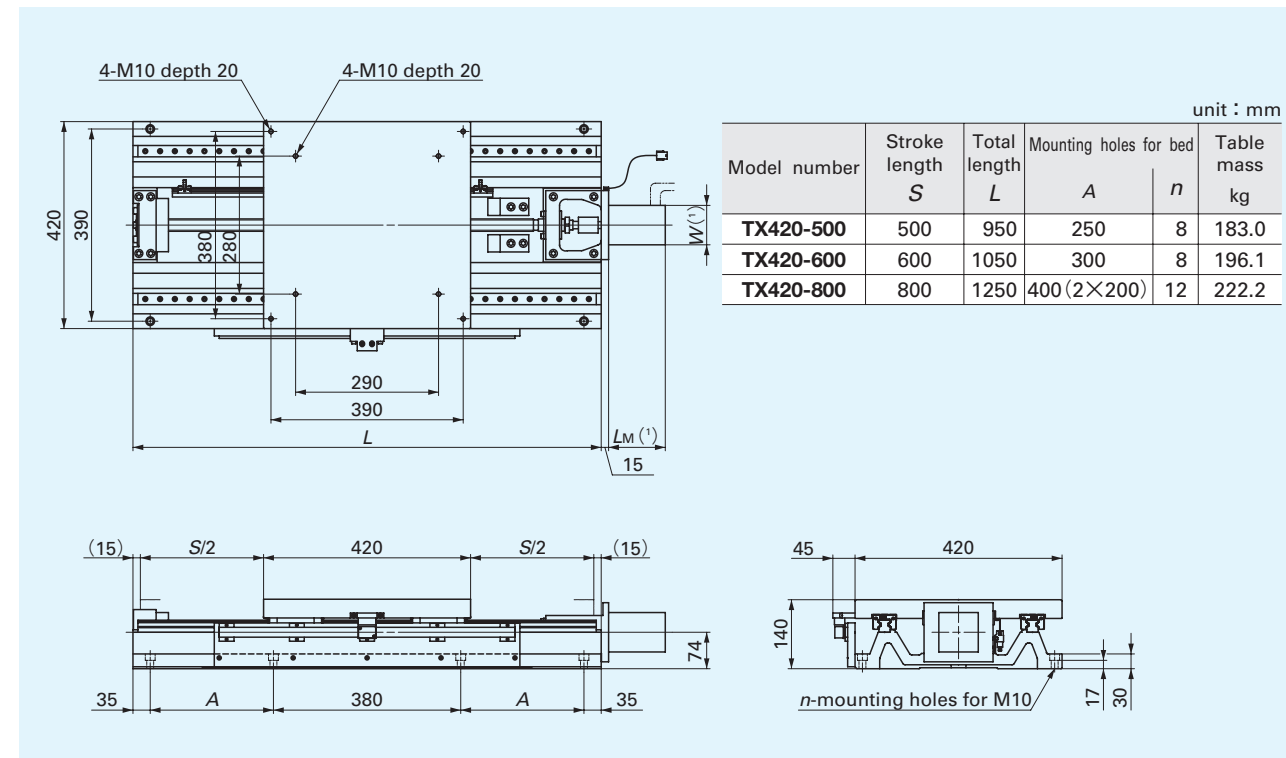
Note⁽¹⁾ : For dimensions of motors, refer page 9-10.
 (2) : Motor weight is not included.

TX320



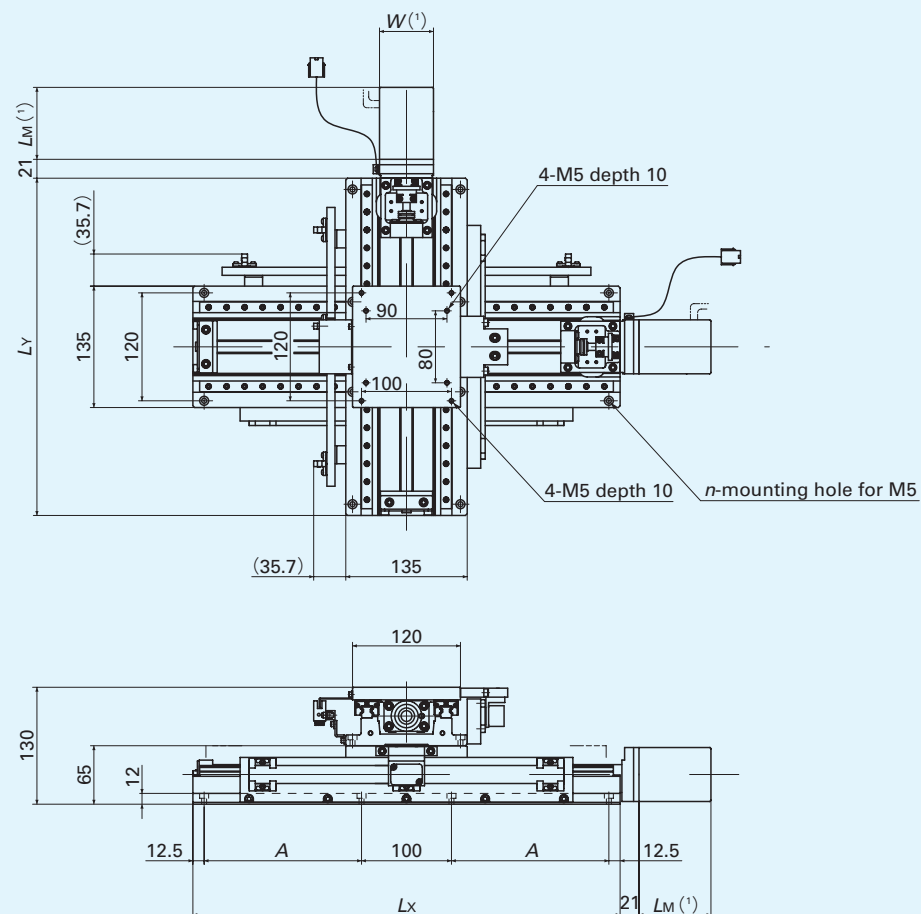
Note⁽¹⁾ : For dimensions of motors, refer page 9-10.
 (2) : Motor weight is not included.

TX420



Note⁽¹⁾ : For dimensions of motors, refer page 9-10.
 (2) : Motor weight is not included.

CTX120



unit : mm

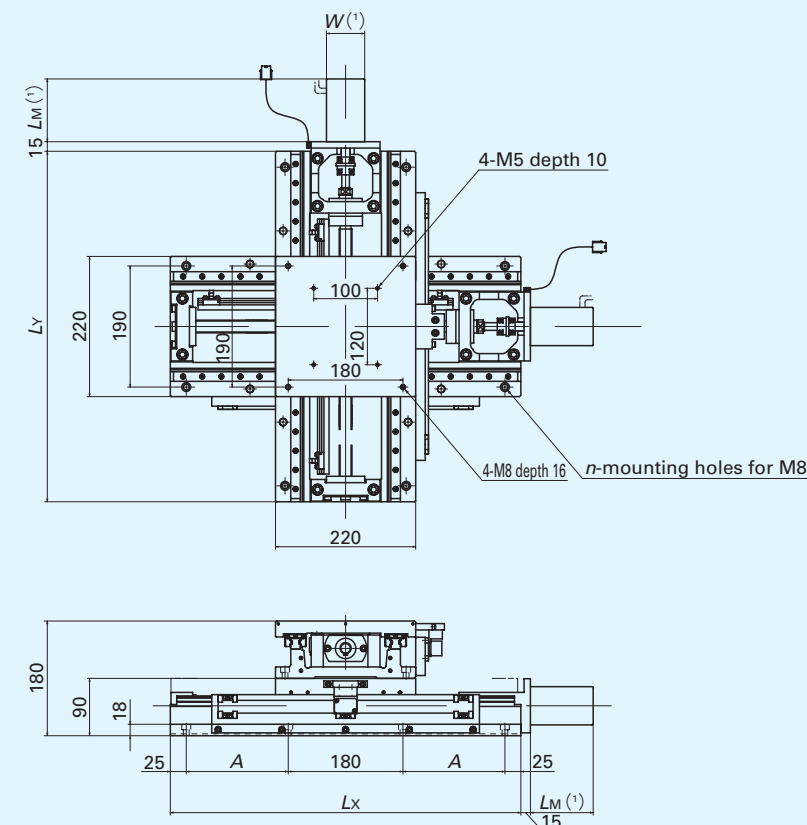
| Model number | Stroke length S | | Total length | | Mounting holes for bed | | Table mass ^(?) kg |
|--------------|-----------------|--------|--------------|-----|------------------------|---|---------------------------------|
| | X-axis | Y-axis | Lx | Ly | A | n | |
| CTX120-1010 | 100 | 100 | 275 | 275 | 75 | 8 | 22.6 |
| CTX120-2010 | 200 | 100 | 375 | 275 | 125 | 8 | 25.3 |
| CTX120-2020 | 200 | 200 | 375 | 375 | 125 | 8 | 28.0 |
| CTX120-3020 | 300 | 200 | 475 | 375 | 175 | 8 | 30.7 |

Note⁽¹⁾ : For dimension of motor, refer page 9-10.

^(?) : Motor weight is not included.

Remark : Different stroke lengths, combination of different table sizes and tables with plastic cable carrier can be available. Consult IIO.

CTX220



unit : mm

| Model number | Stroke length S | | Total length | | Mounting holes for bed | | Table mass ^(?) kg |
|--------------|-----------------|--------|--------------|-----|------------------------|----|---------------------------------|
| | X-axis | Y-axis | Lx | Ly | A | n | |
| CTX220-2020 | 200 | 200 | 450 | 450 | 110 | 8 | 72.8 |
| CTX220-3020 | 300 | 200 | 550 | 450 | 160 | 8 | 77.6 |
| CTX220-3030 | 300 | 300 | 550 | 550 | 160 | 8 | 82.4 |
| CTX220-4030 | 400 | 300 | 650 | 550 | 210 (2×105) | 12 | 87.6 |

Note⁽¹⁾ : For dimension of motor, refer page 9-10.

^(?) : Motor weight is not included.

Remark : Different stroke lengths, combination of different table sizes and tables with plastic cable carrier can be available. Consult IIO.

The Roller Effect

Monster

IKO Linear Roller Way Super X

LRX

IKO

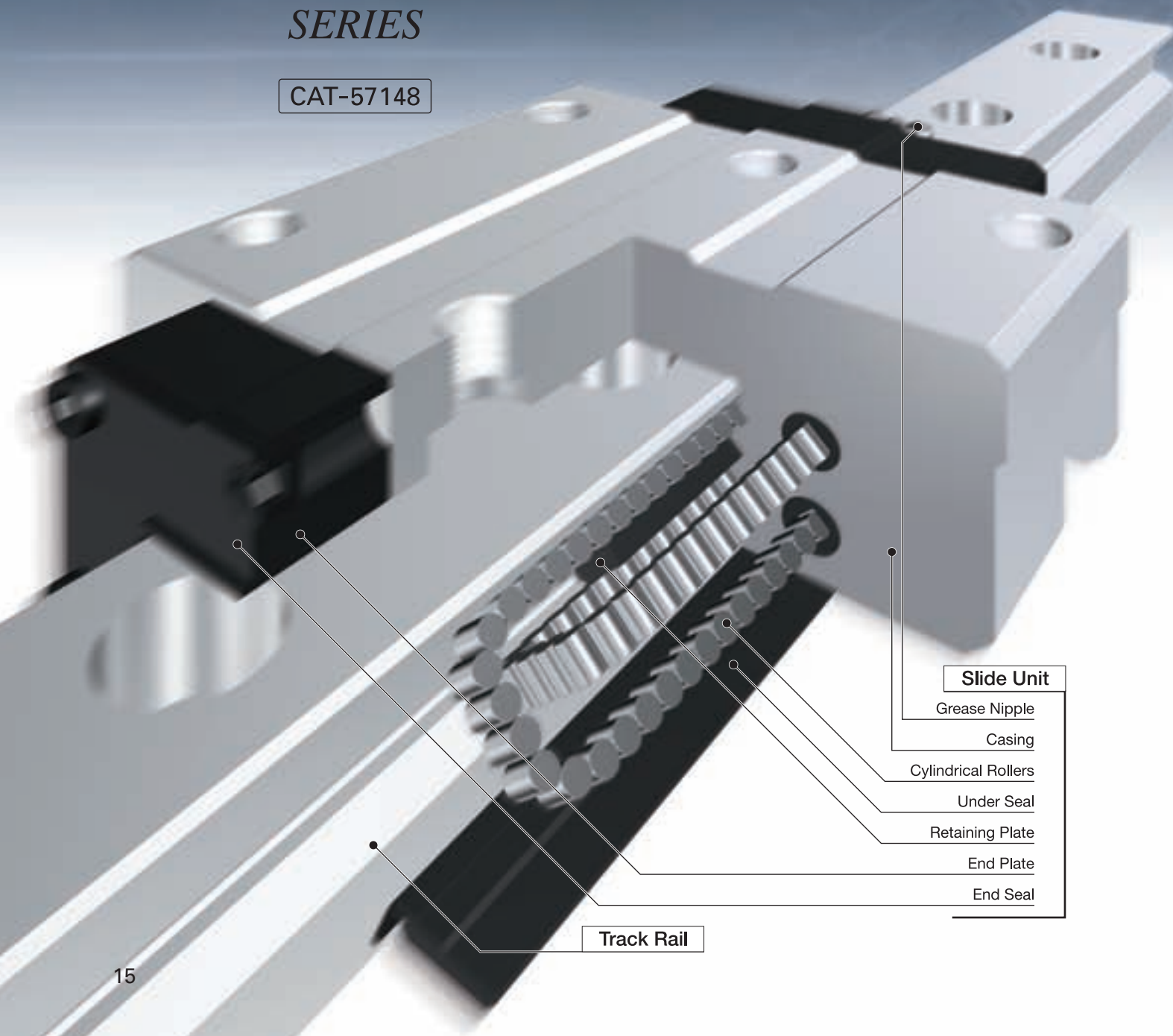
Linear Roller Way

SUPER X

SERIES

CAT-57148

In **IKO** Linear Roller Way Super X, four rows of cylindrical rollers are incorporated in a highly rigid casing with good balance, and the cylindrical rollers in each row are arranged in parallel to each other. Owing to its small elastic deformation, stable operation is ensured even under heavy or fluctuating loads. Smooth and quiet motion, high reliability, high rigidity and high running accuracy are realized.



Slide Unit

Grease Nipple

Casing

Cylindrical Rollers

Under Seal

Retaining Plate

End Plate

End Seal

Track Rail

High Rigidity

Superior Damping Characteristic

Well-balanced Structure

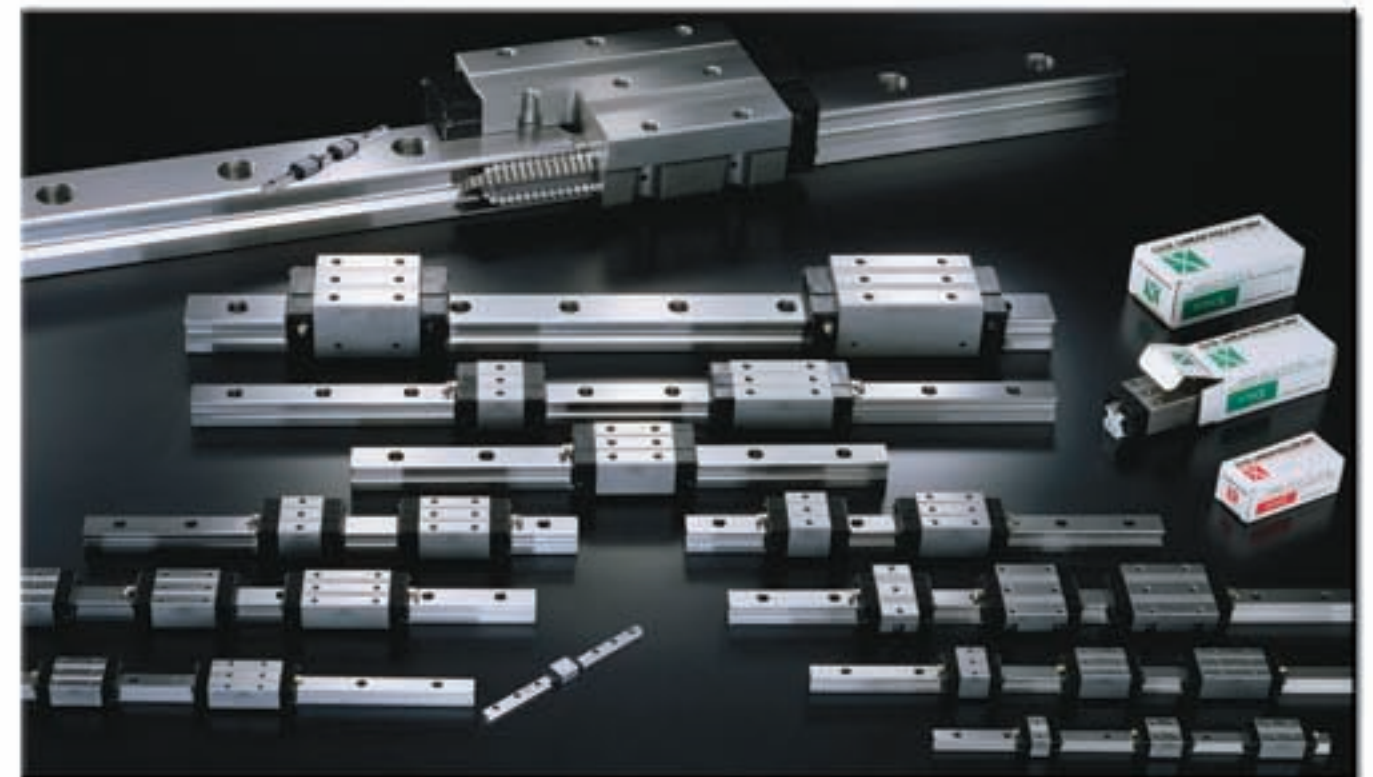
The Super X interchangeable series brings to you the "Six Roller Effects", whenever and wherever they are required to give higher potentials for your application.

High Load Capacity

Long Life and High Accuracy

Smooth and Quiet Motion

In high rigidity and high load capacity **IKO** Linear Roller Way Super X series, the smallest size **LRX 10** is newly introduced covering a full range of variation. Nine types are now available in various sizes with track rail width ranging from 10mm to 100mm. Interchangeable, stainless steel made and nineteen kinds of special options are also available.



NIPPON THOMPSON CO., LTD.

Head office : 19-19 Takanawa 2-chome Minato-ku
Tokyo 108-8586, Japan
Phone : +81 (0)3-3448-5850
Fax : +81 (0)3-3447-7637
E-mail : ntt@ikonet.co.jp
URL : <http://www.ikonet.co.jp/eg/>
Plant : Gifu, Kamakura

NIPPON THOMPSON CO., LTD.

ASEAN REPRESENTATIVE OFFICE
Level 8, #1 Silom Road, Silom
Bangrak, Bangkok
Thailand 10500
Phone: +66 (0)-2-231-8278
Fax: +66 (0)-2-231-8121
E-mail: ntar@ikonet.co.jp

IKO-THOMPSON (SHANGHAI) LTD.

Unit G, 23rd Floor, Zhao Feng World Trade Building
No.369, Jiang Su Road
Changning District, Shanghai 200050
People's Republic of China
Phone: +86 (0)21-5237-9100
Fax: +86 (0)21-5237-9095
E-mail: ntc@ikonet.co.jp

IKO INTERNATIONAL, INC.

<http://www.ikonet.com/>

East coast

91 Walsh Drive
Parsippany, NJ 07054
U.S.A.
Phone: +1 973-402-0254
Toll Free: 1-800-922-0337
Fax: +1 973-402-0441
E-mail: eco@ikonet.co.jp

Midwest

500 East Thorndale Avenue
Wood Dale, IL 60191
U.S.A.
Phone: +1 630-766-6464
Toll Free: 1-800-323-6694
Fax: +1 630-766-6869
E-mail: mwo@ikonet.co.jp

West coast

20170 South Western Avenue
Torrance, CA 90501
U.S.A.
Phone: +1 310-609-3988
Toll Free: 1-800-252-3665
Fax: +1 310-609-3916
E-mail: wco@ikonet.co.jp

Southeast

2150 Boggs Road, Suite 100
Duluth, GA 30096
U.S.A.
Phone: +1 770-418-1904
Toll Free: 1-800-874-6445
Fax: +1 770-418-9403
E-mail: seo@ikonet.co.jp

Southwest

8105 N. Beltline Road
Suite 130, Irving, TX 75063
U.S.A.
Phone: +1 972-929-1515
Toll Free: 1-800-295-7886
Fax: +1 972-915-0060
E-mail: swo@ikonet.co.jp

NIPPON THOMPSON EUROPE B.V.

<http://www.ikonet.eu/>

The Netherlands

Sheffieldstraat 35-39
3047 AN Rotterdam
The Netherlands
Phone: +31 (0)10-4626868
Fax: +31 (0)10-4626099
E-mail: nte@ikonet.co.jp

Germany

Mündelheimer Weg 56
40472 Düsseldorf
Germany
Phone: +49 (0)211-414061
Fax: +49 (0)211-427693
E-mail: ntd@ikonet.co.jp

Im Gewerbepark D 30
93059 Regensburg
Germany
Phone: +49 (0)941-206070
Fax: +49 (0)941-2060719
E-mail: ntdr@iko-nt.de

Gruben Str.95c
66540 Neunkirchen
Germany
Phone: +49 (0)6821-999-860
Fax: +49 (0)6821-999-8626
E-mail: ntdn@iko-nt.de

UK

2 Vincent Avenue, Crownhill
Milton Keynes Bucks MK8 0AB
United Kingdom
Phone: +44 (0)1908-566144
Fax: +44 (0)1908-565458
E-mail: sales@iko.co.uk

Spain

Autovia Madrid-Barcelona, Km. 43,700
Polig. Ind. AIDA, A-8, Ofic. 2, 1^a
19200-Azuqueca de Henares
Guadalajara, Spain
Phone: +34 949-263390
Fax: +34 949-263113
E-mail: nts@ikonet.co.jp

France

Roissypole Le Dôme
2 rue de La Haye
BP 15950 Tremblay en France
95733 Roissy C. D. G. Cedex
France
Phone: +33 (0)1-48165739
Fax: +33 (0)1-48165746
E-mail: ntf@ikonet.co.jp

Recognizing that conservation of the global environment is the top-priority challenge for the world's population, **IKO** will conduct its activities with consideration of the environment as a corporate social responsibility, reduce its negative impact on the environment, and help foster a rich global environment.

**ISO 9001 & 14001 Quality system
registration certificate**

